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# WEYL GROUP OF SPECIAL LINEAR ALGEBRA

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Abstract- In this paper we discuss about the Root space decomposition of Special Linear Algebra. We show that the Weyl group of Special Linear Algebra sl(n, F) is the permutation group on n symbols. The weyl group of  $A_3$  is calculated.

Keywords:Special linear algebra, Root space decomposition, Weyl group.

Subject Classifications: 17B22.

# I. INTRODUCTION

**Definition (Lie algebra).** A Lie algebra is a vector space *L* over a field *F*, with an operation

[,]:  $L \times L \rightarrow L$ , denoted  $(x, y) \mapsto [x, y]$ ,(called the bracket or commutator of x and y), satisfying the following properties :

(L1) The bracket operation is bilinear.

(L2) [x, x] = 0, for all  $x \in L$ .

(L3) [x, [y, z]] + [y, [z, x]] + [z, [x, y]] = 0, for all  $x, y, z \in L$ .

(L3) is called the Jacobi identity.

0 = [x + y, x + y] = [x, x] + [x, y] + [y, x] + [y, y] = [x, y] + [y, x]

Hence, condition (L1) and (L2) implies

(L2') [x, y] = -[y, x] (anticommutativity), for all  $x, y \in L$ .

If char  $F \neq 2$ , then putting x = y in (L2'), shows that (L2') implies (L2).

Lie Subalgebra: A subspace K of a Lie algebra L is called a subalgebra if  $[x, y] \in K$ , whenever  $x, y \in K$ .

Unless specifically stated, we shall be concerned with Lie algebras L whose underlying vector space is finite dimensional.

Some Examples:

(1) Any vector space V, with [x, y] = 0, for all  $x, y \in V$  is a Lie algebra called Abelian Lie algebra. In particular, the field F may be regarded as a 1dimensional abelian Lie algebra.

(2) Let V be a finite dimensional vector space over F with  $\dim(V) = n$ . Let End V be the set of all linear transformations from  $V \rightarrow V$ . This is again a vector space over F of dimension  $n^2$ .

 $x_2$ )

Define an operation on End V, by [x, y] = xy - yx.

With this operation End V becomes a lie algebra over

$$F.[x_1 + x_2, y] = (x_1 + x_2)y - y(x_1 + y_2)y - y(x_1 + y_$$

 $= x_1 y + x_2 y - y x_1 - y x_2$ 

 $= (x_1y - yx_1) + (x_2y - yx_2)$ 

 $= [x_1, y] + [x_2, y]$  for all  $x_1, x_2, y \in End V$ .

Similarly,  $[x, y_1+y_2] = [x, y_1] + [x, y_2]$ , for all  $x, y_1, y_2 \in End V$ .

(L2) [x, x] = xx - xx = 0, for all  $x \in End V$ .

(L3)[x, [y, z]] + [y, [z, x]] + [z, [x, y]]

= [x, (yz - zy)] + [y, (zx - xz)] + [z, (xy - yx)]

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= (x(yz - zy) - (yz - zy)x) + (y(zx - xz) - (zx - xz)y) + (z(xy - yx) - (xy - yx)z)

= xyz - xzy - yzx + zyx + yzx - yxz - zxy + xzy + zxy - zyx- xyz + yxz

= 0:

End V (also written gl(V)) is called General linear algebra. Any subalgebra of a Lie algebra gl(V) is called a linear Lie algebra. gl(V) can be identified with the set of all  $n \times n$  matrices over F, denoted gl(n, F), with the Lie bracket defined by

[x, y] = xy - yx

where *xy* is the usual product of the matrices *x* and *y*. As a vector space, gl(n, F) has a basis consisting of the matrix units  $\boldsymbol{e}_{ij}$  for  $1 \leq i, j \leq n$ . Here,  $\boldsymbol{e}_{ij}$  is the  $n \times n$  matrix which has 1 in the *i* - *j* position and 0 elsewhere.

 $As_{\theta_{ij}} e_{kl} = \delta_{jk} e_{ll}$ 

It follows that:  $[e_{ij}, e_{kl}] = \delta_{jk}e_{il} - \delta_{ll}e_{kj}$ . where  $\delta$  is the kronecker delta, defined by,

where b is the kronecker denta, defined by,

 $\delta_{ij} = 1$ , if i = j and  $\delta_{ij} = 0$ , if  $i \neq j$ .

# Classical Lie algebras An

(2) An: Let dim V = n + 1. Denote the set of all endomorphism's of V having trace zero, by sl(V) or sl(n + 1, F). (Trace of a square matrix is the sum of its diagonal entries). Since Tr(xy) = Tr(yx) and Tr(x + y) = Tr(x) + Tr(y), sl(V) is a subalgebra of gl(V), called the Special Linear algebra.sl(V) is a proper subalgebra of gl(V). sl(V) has a basis consisting of the e<sub>ij</sub> for i≠ j together with e<sub>if</sub> - e<sub>i+1,i+1</sub> for 1 ≤i≤n.

Adjoint representation:

## Themap

 $ad:L \rightarrow DerLsendingxtoadx$ iscalledadjointrepres entationofL.

**Derivation:**Aderivation of Visalinear map*D*:  $V \times V \rightarrow V$  such that D(ab) = aD(b)+D(a)b, for all  $a, b \in V$ . Let *Der V* be the set of derivations of *V*. This set is closed under addition and scalar multiplication and

contains the zero map. Hence, Der V is a vector subspace of gl(V).

**Ideals:** A subspace *I* of a Lie algebra *L* iscalled an ideal of L if  $[x, y] \in I$ , for all  $x \in L$ ,  $y \in I$ .

**Derived series:** A derived series of a LieAlgebra *L* is a sequence of ideals of *L* defined by  $L^{(0)} = L, L^{(1)} = [L, L], L^{(2)} = [L^{(1)}, L^{(1)}], \dots, L^{(i)} = [L^{(i-1)}, L^{(i-1)}].$ 

**Solvable:** A Lie Algebra L is called Solvable f  $L^{(n)} = 0$  for some n.

**Radical:** Let *L* be an arbitrary Lie algebraand let *S* be a maximal solvable ideal. If I is any otherSolvable ideal of L, then S+I = S. By maximality of S, we get S + I = S, or  $I \square S$ . This proves the existence of a unique maximal solvable ideal, called the radical of L and denoted Rad L.

**Semisimple:** A Lie algebra *L* is called semisimpleif Rad L = 0.

**RootSystem:**AsubsetФofaEuclideanspaceEiscal ledarootsysteminEifitsatisfiesthefollowingations

(R1)  $\Phi$  is finite, spansE, and does not contain 0.

(R2)If  $\alpha \in \Phi$ , the only multiples of  $\alpha$  in  $\Phi$  are  $\pm \alpha$ .

(R3) If  $\alpha \in \Phi$ , the reflection  $\sigma_{\alpha}$  permutes the elements of  $\Phi$ .

(R4) If  $\alpha$ ,  $\beta \in \Phi$ , then  $\langle \beta, \alpha \rangle \in \mathbb{Z}$ .

**Rank**. The dimension of *E* is called the rank of the root system  $\Phi$ .

ThebaseforaRootsystemandWeylgroup:

**Base:** A subset  $\Delta$  of  $\Phi \subseteq V$  is called abaseif, (B1)  $\Delta$  is a basis of V,

(B2) Each root  $\beta$  in  $\Phi$  can be written s,

Where the coefficients  $k_{\alpha}$  are either all nonnegative int egers or all non-

positiveintegers. Therootsin∆arecalled simple roots.

#### The Weyl group of a root system:

For each root  $\alpha \in \Phi$  the reflection  $\sigma_{\alpha}$  is an invertible lineartransformation on *E*. The subgroup of *GL(E)* of invertiblelinear transformations of *E* generated by the reflections  $\sigma_{\alpha}$  ( $\alpha \in \Phi$ ) is known as the Weyl group of  $\Phi$ , denoted by *W*.

**Lemma:** The Weyl group W associated to  $\Phi$  finite.

**Theorem:** Every root system  $\Phi$  has abase.

**Weyl chamber:** The Weyl chambers are defined to be the components of the complement in E of the union of all hyperplanes perpendicular to the roots. Each regular  $\gamma \in E$ , therefore belongs to precisely one(connected component)weyl chamber of  $E \setminus \bigcup_{\alpha} P_{\alpha}$ , denoted  $\zeta(\gamma)$ . The elements of weyl group *W* are orthogonal and permute the roots. Therefore, the weyl group *W* permutes the Weyl chambers.

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## **Root space decomposition**

Asubalgebra is called toral if it consists of semisimple elements. Any toral subalgebra is abelian by the following reasoning. Let *T* be toral,  $x \in T$ , so adx is semisimple and so over an algebraically closed *F* it is diagonalizable. So if ad x has only 0 eigenvalues, then ad x = 0. Suppose it has an eigenvalue  $a \neq 0$ , i.e. there is a  $y \in T$ , such that [x, y] = ay. Since *y* is also semisimple, so is ad y and it has linearly independent eigenvectors  $y_1 = y, \dots, y_m$  (since ad(y)(y) = 0) of eigenvalues 0,  $b_2, \dots, b_m$ , we can write *x* in this basis as  $x = a_1 y_1 + \dots + a_m y_m$ . Then  $-a_y = ady(x) = 0.y + b_2 a_2 y_2 + \dots$ , i.e. *y* is a linear combination of the other eigenvectors, which is impossible. So a = 0 and ad x = 0 for all  $x \in T$ , i.e. [x, y] = 0 for all  $x, y \in T$ .

Let *H* be a maximal toralsubalgebra of *L*, i.e. not included in any other. For any  $h_{\underline{1},\cdot}h_{\underline{2}} \in H$ , we have  $adh_1 \circ adh_2(x) = [h_1, [h_2, x]] = -[h_2, [x, h_1]] - [x, [h_1, h_2]] = [h_2, [h_1, x]] = adh_2 \circ adh_1(x)$  by the Jacobi identity, so adL H consists of commuting semisimple endomorphism's and by astandard theorem in linear algebra these are simultaneously diagonalizable. So we can find Eigen spaces  $L\alpha = \{x \in L \mid [h,x] = \alpha(h)x$  for all  $h \in H\}$  for  $\alpha \subset H^*$ , such that they form a basis of *L*, i.e. we can write the **Root space decomposition** 

(or Cartan decomposition)

$$L = (\underline{L}(H) \bigoplus \coprod_{\alpha \in \Phi} L_{\alpha})$$

**Theorem:** Let *H* be a maximal toral subalgebra of *L*. Then  $H = C_L(H)$ .

**Root Space Decomposition of** sl(n + 1, F): Let *H* consist of the diagonal matrices in the algebra sl(n + 1, F) of all  $(n + 1) \times (n + 1)$  matrices with trace zero.

$$H = \{ \begin{pmatrix} a_1 & 0 & \cdots & 0 \\ 0 & a_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & a_{n+1} \end{pmatrix} | a_1 + a_2 + \cdots + a_{n+1} = 0 \}$$

$h_1 =$	(1 0 0 0	0 -1 0 :: 0	0 0 :: 0	 \ 	0 0 0  0
$h_2 =$	(0 0 0 0	0 1 0  0	0 0 1 : 0	 \ 	0 0 0 0
i h <sub>n</sub> =	( 0 0 0 0	0 0  0 0	0 0 :	 \ 1 0	0 0 :: 0 -1

Let  $\epsilon_i \in H^*$  denote the linear function which assigns to each diagonal matrix its *i*<sup>th</sup> (diagonal) entry,

i.e. if 
$$h = \begin{pmatrix} a_1 & 0 & \cdots & 0 \\ 0 & a_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & a_{m+1} \end{pmatrix} \in H$$
  
 $\epsilon_i(h) = a_i[h, e_{ij}] = he_{ij} - e_{ij}h = a_ie_{ij} - a_je_{ij}$   
 $= \epsilon_i(h)e_{ij} - \epsilon_j(h)e_{ij} = (\epsilon_i - \epsilon_j)(h)e_{ij}$   
 $\therefore [h, e_{ij}] = (\epsilon_i - \epsilon_j)(h)e_{ij}$ , for all  $h \in H$ .

Thus, we see that  $\mathbf{e}_{ij}$  is a joint eigenvector for the maps ad (h) with  $h \in H$  and with eigenvalue  $\epsilon_i - \epsilon_j \in H^*$ . This shows that H is a maximal commutative subalgebra of sl(n + 1, F). Any  $x \in sl(n + 1, F)$  can be written as the sum f some element  $h' \in H$  and the matrices  $e_{ij}$  with  $i \neq j$ . Vanishing of [h, x], for all  $h \in H$  then immediately implies that all the coefficients of the  $\boldsymbol{e}_{ii}$  have to vanish. On the other hand, for any element  $h \in H$  the map ad (h) :sl(n + 1, F)  $\rightarrow$  sl(n + 1, F) is diagonalizable, so H is a MaximalToralsubalgebra of sl(n + 1, F).

The linear functions of the form  $\Phi = \{ \epsilon_i - \epsilon_j : i \neq j \}$  are the roots of sl(n + 1, F) relative to H.Each of the root spaces  $sl(n + 1, F) = \{x \in sl(n + 1, F) | [h, x] \}$  $(\boldsymbol{\epsilon}_{i} - \boldsymbol{\epsilon}_{i})(h)x$  is one dimensional and spanned by  $\boldsymbol{e}_{ii}$ .

The Root Space Decomposition (or Cartan decomposition)of sl(n + 1, F) is given by,

 $sl(n+1, F) = H \bigoplus \bigoplus_{i \ge j} (F e_{ij} \bigoplus F e_{ji})$ 

## Cartan matrix of sl(n + 1, F):

The base for sl(n + 1, F) is given by  $\{\alpha_i = \epsilon_i - \epsilon_{i+1}\}$ . Thismeans that for any two consecutive simple roots we have  $\langle \alpha_i, \alpha_{i+1} \rangle = \langle \alpha_{i+1}, \alpha_i \rangle = -1, \langle \alpha_i, \alpha_i \rangle = 2$ , and  $< \alpha_i, \alpha_i > = 0$  otherwise. This gives the following Cartan matrix of type  $A_n$ 

$$\begin{pmatrix} 2 & -1 & 0 & 0 & \cdots & 0 \\ -1 & 2 & -1 & 0 & \cdots & 0 \\ 0 & -1 & 2 & -1 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & \cdots & 2 & -1 \\ 0 & 0 & 0 & \cdots & -1 & 2 \end{pmatrix}$$

Thus the Cartan matrix of sl(n + 1, F) has each entry on the main diagonal equal to 2, in the two diagonals above and below the main diagonal all entries equal -1, while allother entries are zero.

## Weyl group of $A_n$

The Weyl group is generated by reflections in the hyper planesorthogonal to the roots and thus consist only of orthogonaltransformations. Consider the orthonormal basisof the root space such that the coordinates of any root are integers between -2 and 2. The simple roots of  $A_n$  are given by  $\alpha_i = \{e_i - e_{i+1}: 1 \le i \le n\}$  Consider the reflection or ar

$$\begin{aligned} \sigma_{\alpha_i}(\theta_i) \\ &= \sigma_{\theta_i - \theta_{i+1}}(\theta_i) \\ &= \theta_i - \frac{2(\theta_i, \theta_i - \theta_{i+1})}{(\theta_i - \theta_{i+1}, \theta_i - \theta_{i+1})} (\theta_i - \theta_{i+1}) \end{aligned}$$

$$= \theta_{l} - \frac{2((e_{l}, e_{l}) - (e_{l}, e_{l+1}))}{(e_{l}, e_{l}) - (e_{l}, e_{l+1}) - (e_{l+1}e_{l}) - (e_{l+1})} (\theta_{l} - \theta_{l+1})$$

$$= \theta_{l} - \frac{2(1 - 0)}{(1 - 0 - 0 + 1)} (\theta_{l} - \theta_{l+1})$$

$$= \theta_{l} - (\theta_{l} - \theta_{l+1})$$

$$= \theta_{l} - (\theta_{l} - \theta_{l+1})$$

$$= \theta_{l+1}$$

$$\sigma_{\alpha_{l}} (\theta_{l+1})$$

$$= \theta_{l+1} - \frac{2(\theta_{l+1}, \theta_{l} - \theta_{l+1})}{(e_{l} - e_{l+1}) - (e_{l+1}, e_{l+1})} (\theta_{l} - \theta_{l+1})$$

$$= \theta_{l+1} - \frac{2((\theta_{l+1}, e_{l}) - (\theta_{l+1}, \theta_{l+1}))}{(e_{l} - \theta_{l+1}) - (e_{l+1}, e_{l+1}) - (\theta_{l+1}, \theta_{l+1})} (\theta_{l} - \theta_{l+1})$$

$$= \theta_{l+1} - \frac{2((\theta_{l+1}, \theta_{l}) - (\theta_{l+1}, \theta_{l+1}))}{(e_{l} - \theta_{l+1}) - (e_{l+1}, \theta_{l+1}) - (\theta_{l+1}, \theta_{l+1})} (\theta_{l} - \theta_{l+1})$$

$$= \theta_{l+1} - \frac{2((\theta_{l+1}, \theta_{l}) - (\theta_{l+1}, \theta_{l+1}))}{(1 - 0 - 0 + 1)} (\theta_{l} - \theta_{l+1})$$

$$= \theta_{l} + 1 - \frac{2((\theta_{l}) - \theta_{l+1})}{(1 - 0 - 0 + 1)} (\theta_{l} - \theta_{l+1})$$

$$= \theta_{l} + 1 - \frac{2((\theta_{l}) - \theta_{l+1})}{(\theta_{l} - \theta_{l+1})} = \theta_{l}$$
For  $j \neq i, i + 1$ 

$$\sigma_{\alpha_{l}} (\theta_{j})$$

$$= \theta_{l} - \frac{2((\theta_{l}, \theta_{l}) - (\theta_{l+1}, \theta_{l}) - (\theta_{l+1}, \theta_{l+1})}{(\theta_{l} - \theta_{l+1}) - (\theta_{l+1}, \theta_{l+1}) - (\theta_{l} - \theta_{l+1})} = \theta_{l} - \frac{2((\theta_{l}, \theta_{l}) - (\theta_{l}, \theta_{l+1}) - (\theta_{l+1}, \theta_{l+1})}{(\theta_{l} - \theta_{l+1}) - (\theta_{l+1}, \theta_{l+1}) - (\theta_{l+1}, \theta_{l+1})} = \theta_{l} - \frac{2((\theta_{l}, \theta_{l+1}) - (\theta_{l+1}, \theta_{l+1})}{(\theta_{l} - \theta_{l+1}) - (\theta_{l} - \theta_{l+1})} = \theta_{l} - \frac{2((\theta_{l}, \theta_{l+1}) - (\theta_{l}, \theta_{l+1})}{(\theta_{l} - \theta_{l+1}) - (\theta_{l} - \theta_{l+1})} = \theta_{l} - \frac{2((\theta_{l}) - \theta_{l+1}) - (\theta_{l+1}, \theta_{l+1})}{(\theta_{l} - \theta_{l+1}) - (\theta_{l} - \theta_{l+1})} = \theta_{l} - \frac{2((\theta_{l}) - \theta_{l+1})}{(\theta_{l} - \theta_{l+1}) - (\theta_{l+1}, \theta_{l+1}) - (\theta_{l+1}, \theta_{l+1})} = \theta_{l} - \frac{2((\theta_{l}) - \theta_{l+1})}{(\theta_{l} - \theta_{l+1})} = \theta_{l} - \frac{2(\theta_{l}) - \theta_{l+1}}{(\theta_{l} - \theta_{l+1})} = \theta_{l} - \theta_{l} - \theta_{l+1} - \theta_{$$

T

$$e_i \mapsto e_{i+1}$$
  
 $e_{i+1} \mapsto e_i$   
 $e_i \mapsto e_i \text{ for } j \neq i, i+1$ 

Thus,  $a_{x_i}$  generate all possible permutations of the n +1 coordinates. We thus see that the weyl group of sl(n+1,F)is the permutation group  $S_{n+1}$  on n + 1 symbols.

## Weyl group of A3

Therootsystem of sl(n +

1,F)consistsofvectorsoftheform  $\alpha_{kl} =$ То e<sub>kk</sub> en. simplify calculations, identify eachering with unit vector  $\boldsymbol{\epsilon}_k$ . We now have the set of roots  $\{\boldsymbol{\epsilon}_i - \boldsymbol{\epsilon}_i | i \neq j\}$ . The simple roots are  $\alpha_{i} = c_{i}$  $c_{i+1}$ 

Then for  $A_3$  we have theroot system,

$$\begin{split} \Phi &= \{\pm \alpha_1 = \pm (1, -1, 0, 0), \ \pm \alpha_2 = \pm (0, 1, -1, 0), \\ \pm \alpha_3 = \pm (0, 0, 1, -1), \\ \pm \alpha_4 = \pm (1, 0, -1, 0), \ \pm \alpha_5 = \pm (1, 0, 0, \\ -1), \ \pm \alpha_6 = \pm (0, 1, 0, -1) \}. \end{split}$$

The baseis

$$\Delta = \{\alpha_1 = (1, -1, 0, 0), \alpha_2 = (0, 1, -1, 0), \alpha_3$$

= 0, 1, -1).

To find the element of the Weyl group generated by  $\alpha_1 = (1, -1, 0, 0)$  we calculate  $\sigma_{\alpha_1}$  for each of the roots in  $\Phi$ .

$$\begin{split} &\sigma_{\alpha_1}(\alpha_1) = -\alpha_1 \sigma_{\alpha_1}(-\alpha_1) \\ &= \alpha_1 \cdot \sigma_{\alpha_1}(\alpha_2) = \sigma_{\alpha_1}((0, 1, -1, 0)) = (0, 1, 1) - \\ &2 \frac{<(1_x - 1_x - 0_x - 0_x) \cdot (0_x - 1_x - 0_x) \cdot (0_x -$$

Similar calculationsshow:

 $\begin{array}{ll} \sigma \alpha 1(-\alpha_{-}2)=-\alpha 4 & \sigma \alpha 1(\pm \alpha 3)=\pm \alpha 3 & \sigma \alpha 1(\pm \alpha 4)=\pm \alpha 2 \\ \sigma \alpha 1(\pm \alpha 5)=\pm \alpha 6 & \sigma \alpha 1(\pm \alpha 6)=\pm \alpha 5. \\ This gives one element of the Weyl group, namely the permutation \end{array}$ 

 $\{ \pm \alpha_1 \rightleftharpoons \mp \alpha_1, \pm \alpha_2 \rightleftharpoons \pm \alpha_4, \pm \alpha_3 \rightleftharpoons \pm \Box_3, \ , \pm \Box_4 \rightleftharpoons \pm \Box_2, \\ \pm \Box_5 \rightleftharpoons \pm \Box_6, \ , \pm \Box_6 \rightleftharpoons \pm \Box_5 \}.$ 

## Table below shows the permutations with respect toallsimpleroots. Weyl group of A 3:

Reflection	$\pm \alpha_1$	$\pm \alpha_2$	$\pm \alpha_3$	$\pm \alpha_4$	$\pm \alpha_5$	$\pm \alpha_6$
$\sigma_{\alpha_1}$	$\mp \alpha_1$	$\pm \alpha_4$	$\pm \alpha_3$	$\pm \alpha_2$	$\pm \alpha_6$	$\pm \alpha_5$
$\sigma_{\alpha_2}$	$\pm \alpha_4$	$\mp \alpha_2$	±α <sub>6</sub>	$\pm \alpha_1$	$\pm \alpha_5$	$\pm \alpha_3$
$\sigma_{\alpha_3}$	$\pm \alpha_1$	$\pm \alpha_6$	$\mp \alpha_3$	$\pm \alpha_5$	$\pm \alpha_4$	$\pm \alpha_2$

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